

# Hacking Nordic proprietary protocol with GNU Radio

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# Outline

- 1 Nordic Semiconductor 2.4GHz Proprietary solutions
- 2 Bastille Research gr-nordic OOT module
- 3 Building a nrf24L01+ transceiver with GNU Radio
- 4 Conclusion

# Outline

1 - Nordic Semiconductor 2.4GHz Proprietary solutions

2 –

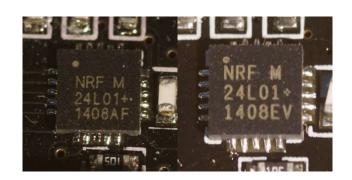
3 –

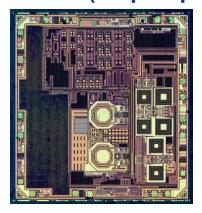
4 –

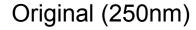
- □ NRF24L01+
  - ☐ Well known by embedded systems guys
  - ☐ This module can be found on Chineese sites for less than 1€

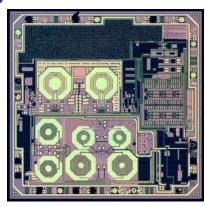


☐ For that price most of them are fake (chip copied)









Fake (350nm)

#### □ NRF24L01+

#### ☐ Inside NRF24L01+ transceiver

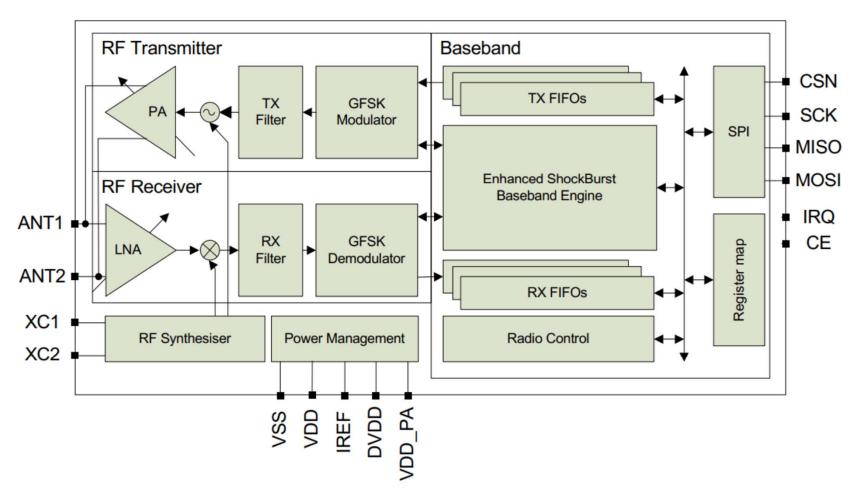


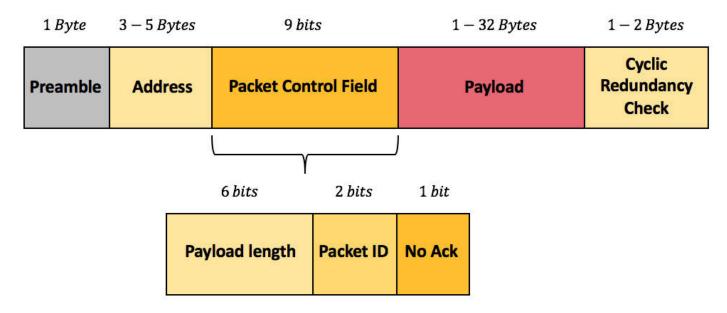
Figure 1. nRF24L01+ block diagram

- □ NRF24L01+
  - Main features:
    - Worldwide 2.4GHz ISM band operation, 126 RF channels
    - GFSK modulation
    - 250kbps, 1 and 2Mbps air data rate
    - Programmable output power: 0, -6, -12 or -18dBm
    - 11.3mA at 0dBm output power
    - 94dBm sensitivity at 250kbps
    - 1 to 32 bytes dynamic payload length with automatic packet handling
    - Host interface : 4-pin hardware SPI
    - 1.9 to 3.6V supply range

https://infocenter.nordicsemi.com/pdf/nRF24L01P PS v1.0.pdf?cp=8 4 0 0

### □ NRF24L01+

### ☐ Enhanced ShockBurst (ESB) protocol



─ Transmission order  →					
PREAMBLE (0x55 or 0xAA)	ADDRESS [3, 5] bytes	PCF 9 bits	PAYLOAD [1, 32] bytes	CRC [1, 2] bytes	
NOTE: ACK PAYLOAD length is [0, 32]			LSBit transmitted first		
		MSBit and MSByte transmitted first			
			MSBit and LSByt	e transmitted first	

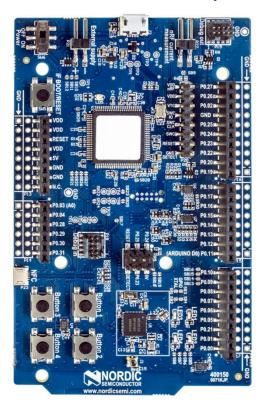
- **☐** Other NRF Chips
  - □ NRF24LU1+ = NRF24L01+ + USB FS + 8051. Found in Microsoft and Logitech keyboards and mice
  - □ NRF24L01+ and NRF24LU1+ are not recommended for new designs



■ More on this dongle later on

# **□** Other NRF Chips

# □ NRF52 series (SoC = RF + ARM Cortex M4) are the replacement chips



NRF52832 DK 40€

, , , , , , , , , , , , , , , , , , , ,		- o p : o : o		
	nRF52810	nRF52811	nRF52832	nRF52840
LTE-M, NB-IoT, GPS				
Bluetooth 5.1 - Direction Finding		(✓)		
Bluetooth 5 - 2 Mbps	✓	✓	✓	/
Bluetooth 5 - Long Range		1		1
Bluetooth mesh	(✔)	(✓)	✓	1
ANT	1	(✓)	1	1
NFC			1	1
Thread, Zigbee, 802.15.4		1		1
CPU	M4	M4	M4F	M4F
Flash (KB)	192	192	256/512	1024
RAM (KB)	24	24	32/64	256
SPI, TWI, UART, PWM	1	1	1	1
High Speed SPI				1
ADC, Comparators	1	1	1	1
I2S, PDM	PDM	PDM	1	1
ARM® TrustZone® Cryptocell				1
USB				1
QSPI				1
GPIO	Up to 32	Up to 32	Up to 32	Up to 48

□ NRF52 series can still use Nordic proprietary protocol (ESB)

- Where do we find NRF Chips
  - ☐ Microsoft and Logitech wireless keyboards and mice
  - **□** Drone remote controllers
  - **□** Sport watches

SIGMA

45.23

- **☐** Bike equipment
- ☐ Heart rate monitors...









- **☐** Well known technology
- Lots of resources about hacks (mice, drones etc,)
- Uses packet communication: interesting to fiddle with it in GNU Radio
- → Goal of this tutorial: to build a Nordic ESB compliant transceiver with GNU Radio
- ☐ Two STM32 boards fitted with NRF24L01+ breakout board transmitting the room temperature every 0.5s (one at 2485MHz and the other at 2500MHz)
- □ STM32 program + PCB shield (available for those interested)



# Outline

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2 - Bastille Research gr-nordic OOT module

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## 2. Bastille Research gr-nordic OOT module

- **□** Do we have to start from nothing?
- Not many up to date implementations
- □ Some of them use the old message queue way of packet transmission, e.g. : <a href="https://github.com/funoverip/gr-cc1111">https://github.com/funoverip/gr-cc1111</a>
- ☐ I came up with the gr-nordic OOT module from Bastille Research
- ☐ Uses GNU Radio message passing interface
- ☐ Has been designed to identify vulnerabilities of wireless keyboards and mice
- ☐ Presented at DEF CON 24 (2016) hacking convention

# MouseJack: Injecting Keystrokes into Wireless Mice

Marc Newlin | marc@bastille.net | @marcnewlin





# ((Mouse Key)Jack KeySniffer)

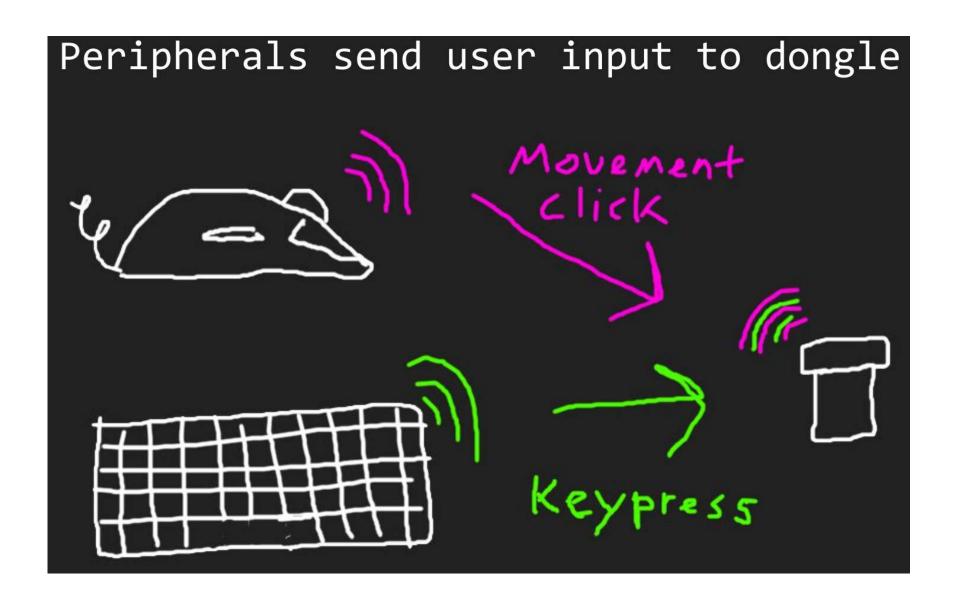
- Wireless mice and keyboards
  - 16 vendors
  - proprietary protocols (non-Bluetooth)
  - 4 families of transceivers
- 16 vulnerabilities
  - keystroke sniffing
  - keystroke injection
  - many are unpatchable

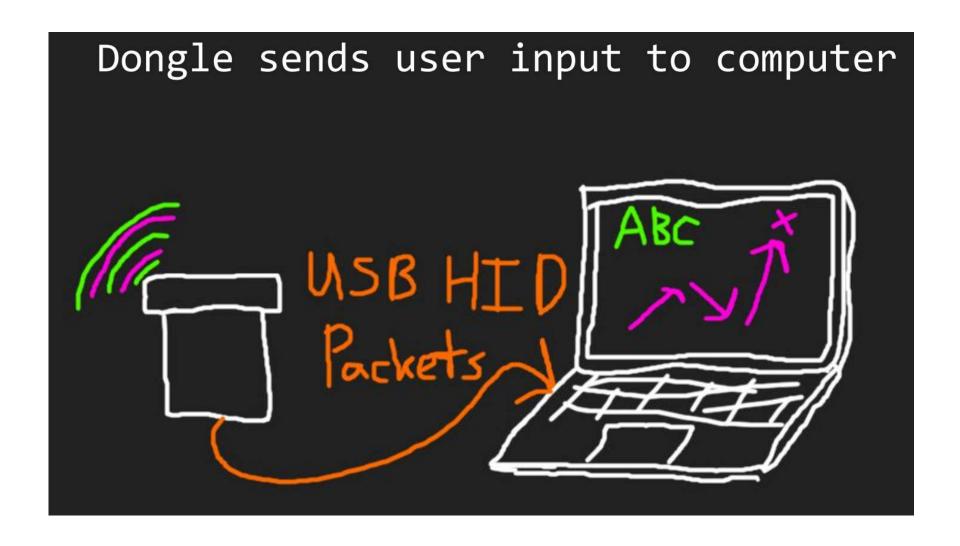


"Since the displacements of a mouse would not give any useful information to a hacker, the mouse reports are not encrypted."

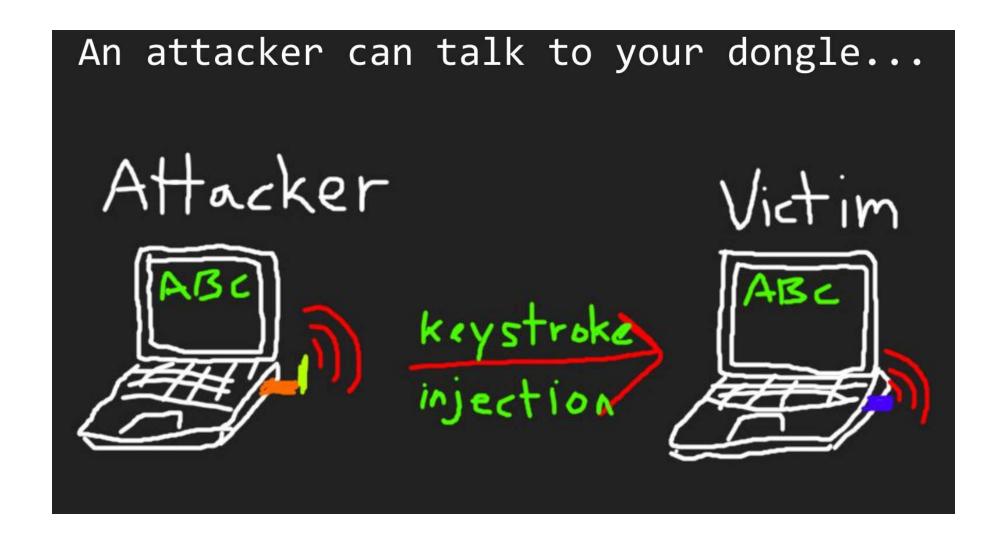
- Logitech (2009)

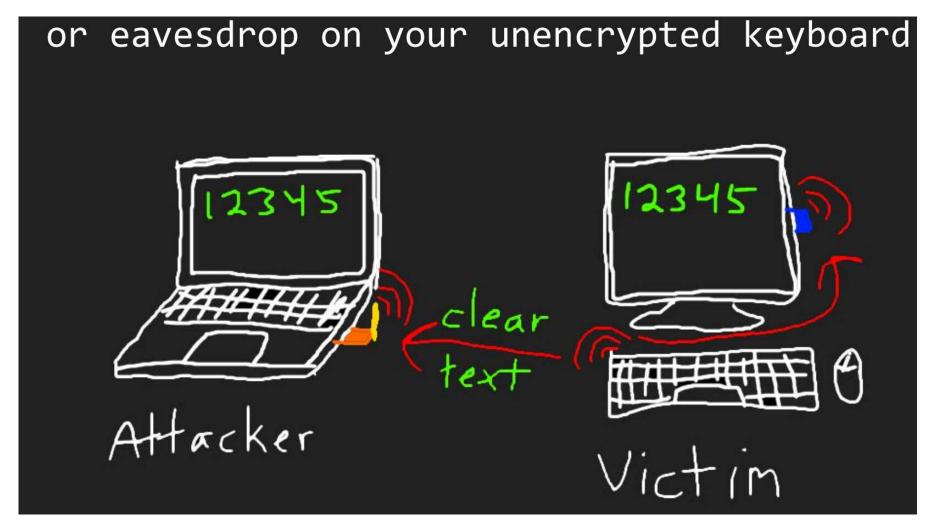
# 2. Bastille Research gr-nordic OOT module





# 2. Bastille Research gr-nordic OOT module





☐ For more details see:

https://github.com/BastilleResearch/mousejack/tree/master/doc/pdf

# Outline

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# □ Let's discover gr-nordic!

# **>** Get and build gr-nordic:

```
>> git clone
https://github.com/BastilleResearch/gr-
nordic.git
>> cd gr-nordic
>> mkdir build
>> cd build
>> cmake ../
>> make -j2
>> sudo make install
>> sudo ldconfig
```

□ Two main blocks:

\* nordic\_tx : input = nordictap\_in message output = stream of uint8\_t

# \* nordic\_rx : input = stream of uint8\_t output = nordictap\_out message

```
nordic rx impl::nordic rx impl(uint8 t channel,
                               uint8 t address length,
                               uint8_t crc_length,
                               uint8 t data rate)
  : gr::sync_block("nordic_rx",
          gr::io_signature::make(1, 1, sizeof(uint8_t)),
          gr::io_signature::make(0, 0, 0)),
          m decoded bits bytes(42*8 /* buffer sufficient for max ESB frame length */),
          m_crc_length(crc_length),
          m_address_length(address_length),
          m_channel(channel),
          m_data_rate(data_rate)
 message port register out(pmt::mp("nordictap out"));
}
```

- > We would like to use these blocks in GRC
- → You can check that this has not been implemented (try it in GRC)



- → Modify nordic\_nordic\_tx.xml and nordic\_nordic\_rx.xml accordingly!
- → Verify that your implementation works in GRC

#### **□** Result

**V1** 

```
<?xml version="1.0"?>
<name>nordic tx</name>
                                   public constructor
  <key>nordic nordic tx</key>
  <category>[Nordic]</category>
  <import>import nordic</import>
  <make>nordic.nordic tx($channel count)</make>
 <param>
   <name>Number of channels
   <key>channel count</key>
   <value>1</value>
   <type>int</type>
 </param>
 <sink>
    <name>nordictap in</name>
    <type>message</type>
 </sink>
 <source>
    <name>out</name>
     <type>byte</type>
    <nports>$channel count
 </source>
 </block>
```

### □ Result

**V1** 

<?xml version="1.0"?> ⊟<block> <name>nordic rx</name> <key>nordic nordic rx</key> <category>[Nordic]</category> <import>import nordic</import> <make>nordic.nordic rx(\$channel, \$address length, \$crc length, \$data rate)</make> <param> <name>RF Channel</name> <key>channel</key> <value>85</value> <type>int</type> </param> <param> <name>Address Length</name> <key>address length</key> <value>5</value> <type>int</type> </param> <param> <name>CRC Length</name> <key>crc length</key> <value>2 <type>int</type> </param> <param> <name>Data Rate</name> <key>data rate</key> <value>2 <type>int</type> </param> <sink> <name>in</name> <type>byte</type> </sink> <source> <name>nordictap out</name> <type>message</type> </source> </block>

- > Let's build a NRF24L01+ receiver with gr-nordic and GRC
- → We have two STM32 boards fitted with NRF24L01+ modules as test transmitters
- They send an Enhanced ShockBurst (ESB) Packet every 0.5s
- Payload is the room temperature. E.g.: 20.0°C
- ESB packet:

Address length	5 bytes		
Address	0x55 0x55 0x55 0x55		
Payload size	8 bytes		
Payload	0x20 0x20 0x20 0x20 + Temp (XX.X)		
CRC length	2 bytes		
Data Rate	2Mbits/s		
RF channel	85 (2485MHz)		

- ➤ Let us first have a try with the existing Python example nordic\_receiver.py
- gr-nordic is said to be SDR agnostic. It uses grosmosdr which does not work with the ADALM-PLUTO.



→ Study nordic\_receiver.py and identify the relevant blocks and their connections

Modifications and the blocks

self.connect(self.qfsk demod, self.rx)

self.nordictap printer = nordictap printer()

# Handle incoming packets

self.msg connect(

```
from gnuradio import iio
self.pluto_source = iio.pluto_source('', int(self.freq), int(self.sample_rate),
                  int (2e6), 0x8000, True, True, True, "manual", 64.0, '', True)
# Receive chain
dr = 0
if args.data rate == 1e6:
                                   V2
    dr = 1
elif args.data rate == 2e6:
   dr = 2
self.rx = nordic.nordic rx(
    args.channel, args.address length, args.crc length, dr)
self.gfsk demod = digital.gfsk demod(
    samples per symbol=args.samples per symbol)
self.lpf = filter.fir filter ccf(
    1, firdes.low pass 2(1, self.sample rate, self.symbol rate / 2, 100e3, 50))
self.connect(self.pluto source, self.lpf)
self.connect(self.lpf, self.gfsk demod)
```

self.rx, "nordictap out", self.nordictap printer, "nordictap in")

Integration of the nordictap\_printer block

→ Create a python file in gr-nordic/python called nordic\_blocks.py, copy the code of nordictap\_printer found in nordic\_receiver.py and paste it into nordic\_blocks.py

→Add nordic\_blocks.py to the module by modifying accordingly CMakeLists.py and \_\_init\_\_.py

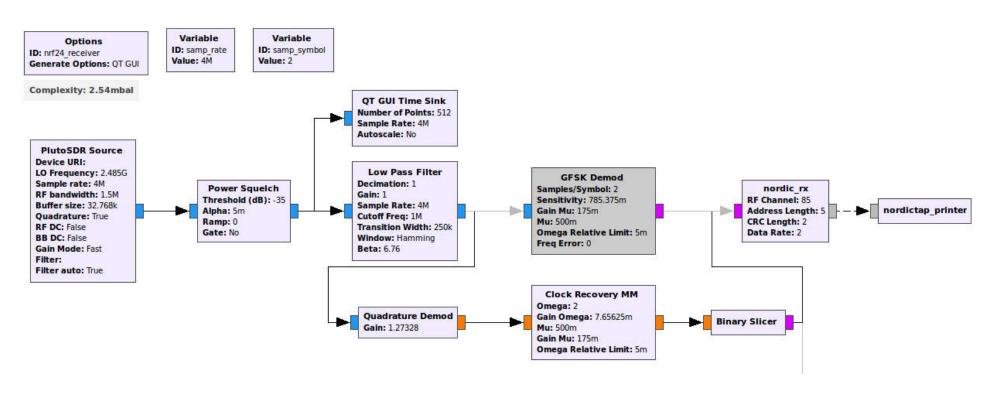
→ Create a GRC xml file for the new nordictap\_printer block

→ Rebuild the module

**V3** 

- > Create a GRC Nordic receiver flowgraph
  - → Using the new blocks and appropriate GNU Radio blocks design a GRC flowgraph receiver
  - → Visualize the incoming packets. Add a power squelch block and synchronize the time sink block with the squelch\_sob tag
  - → Study gfsk.py located in /usr/lib/python2.7/dist-packages/gnuradio/digital and in particular the gfsk\_mod hier block. Expose the blocks that compose gfsk mod

# ☐ This is my receiver:



**V4** 

- ☐ GFSK modulation in a nutshell
- ☐ Is defined by:

$$s(t) = \sqrt{\frac{2E}{T}}\cos(2\pi f_c t + \phi(t, \alpha))$$

- ☐ E is the bit energy, T is the symbol duration and fc is the carrier frequency.
- ☐ Transmitted information is contained in the phase (angle) term:

$$\phi(t,\alpha) = 2\pi h \sum_{i=-\infty}^{\infty} \alpha_i q(t-iT)$$

 $\square$  where  $\alpha_i$  is the message signal (here +1/-1) and:

$$q(t) = \int_{-\infty}^{t} g(\tau) d\tau$$

□ where q(t) describes the shape of the phase transitions whose magnitude is proportional to the modulation index h

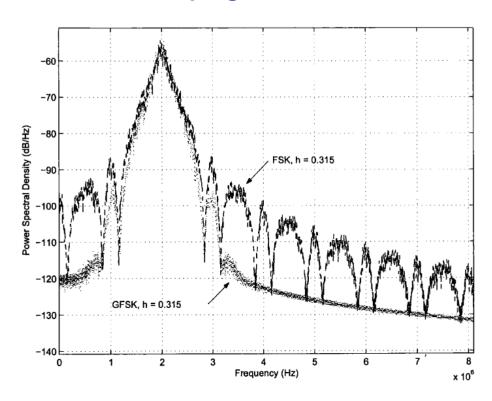
### ☐ We have:

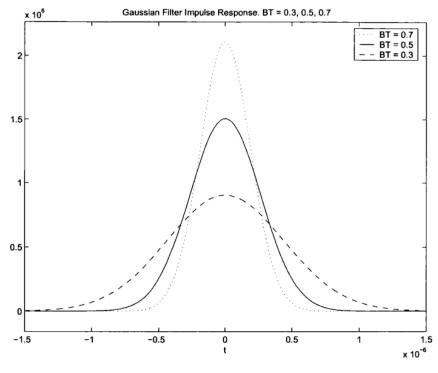
$$h = (f_1 - f_0)T$$

$$= 2f_dT \text{ where}$$

$$f_d = (f_1 - f_c) = (f_c - f_0)$$

# □ Pulse shaping



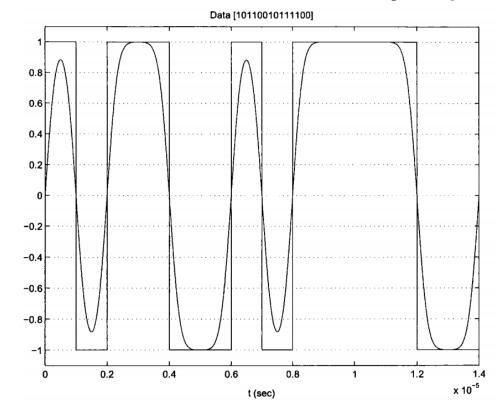


☐ Gaussian filters have an impulse response h(t) given by:

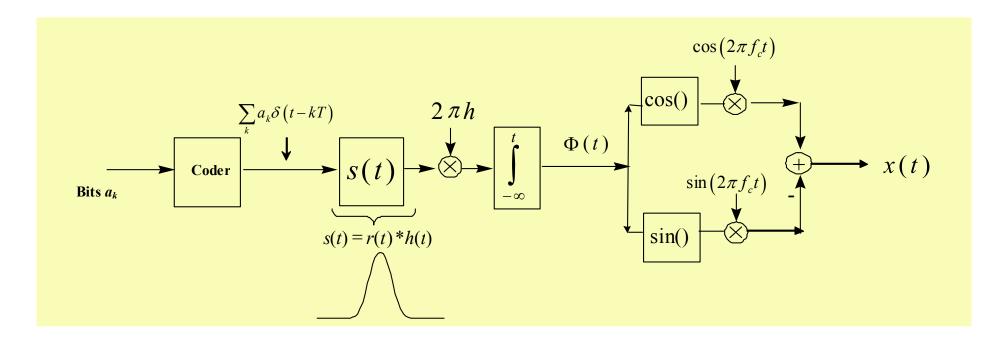
$$h(t) = B\sqrt{\frac{2\pi}{\ln 2}} \exp \frac{-2\pi^2 B^2 t}{\ln 2}$$

☐ B is the filter's -3dB bandwidth. Caracterised by BT product, e.g. BT = 0.5

for Bluetooth.

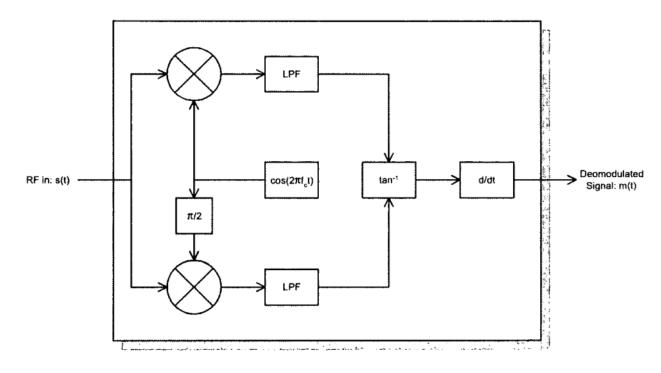


# □ GFSK modulator



→ Have a look in gfsk.py to see how it is done in GNU Radio!

#### □ GFSK demodulator (phase shift discriminator)



#### → We have:

$$s_I(t) = \frac{A(t)}{2} \left[ \cos(4\pi f_c t + 2\pi h \int_{-\infty}^t m(\tau) d\tau) - \cos(2\pi h \int_{-\infty}^t m(\tau) d\tau) \right]$$

$$s_Q(t) = \frac{A(t)}{2} \left[ \sin(4\pi f_c t + 2\pi h \int_{-\infty}^t m(\tau) d\tau) - \sin(2\pi h \int_{-\infty}^t m(\tau) d\tau) \right]$$

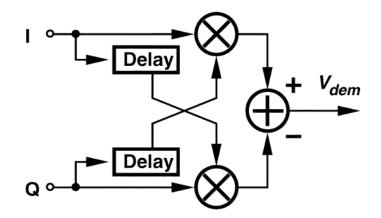
□ After low pass filtering and arctan operation we get:

$$\phi(t) = h \int_{-\infty}^{t} m(\tau) d\tau$$

☐ The differentiation operation leads to:

$$m(t) = \frac{\mathrm{d}(\phi(t))}{\mathrm{d}t}$$

→ Have a look in gfsk.py to see how it is done in GNU Radio! Rather something like that?



- □ Something working behind the scene: Wireshark to decode Nordic ESB packets
- >> sudo apt-get install wireshark
- >> sudo groupadd wireshark
- >> sudo usermod -a -G wireshark #yourusername#
- >> sudo chgrp wireshark /usr/bin/dumpcap
- >> sudo chmod 750 /usr/bin/dumpcap
- >> sudo setcap cap\_net\_raw,cap\_net\_admin=eip

/usr/bin/dumpcap

- >> sudo getcap /usr/bin/dumpcap
- >> cd ~/gr-nordic/
- >> sudo wireshark -X

lua\_script:wireshark/nordic\_dissector.lua -i lo -k -f udp

- ☐ GNU Radio message passing interface and PMTs
- → In the case of packet transmission we are not interested in data streaming. We would like to transmit asynchronous messages.
- → In GNU Radio there are two mecanisms to pass messages:
  - → Synchronously to a data stream, using stream tags
  - → Asynchronously, using the message passing interface
- → From a programming perspective a message can be represented as a data type.
- → In Python, this is not a problem, since it is weakly typed
- → C++ on the other hand is strongly typed, and it is not possible to create a variable without knowing its type
- → In GNU Radio we need to exchange the same data objects between Python and C++ → Polymorphic Types or PMTs

- □ Hence messages are PMTs and can contain anything
   □ Commonly vectors of bytes for PDUs
   □ Or a dictionary (Key: value pair)
- □ We need to understand a minimum how PMTs work. Let's have a look here:

https://wiki.gnuradio.org/index.php/Guided Tutorial Programming Topics#5.1 Polymorphic Types .28PMT.29

- > Let's build a transmitter
- → The nordic\_transmitter block requires a message input block
- → This message has to be a PMT
- → The PMT will be made up of these fields:

```
channel index = 0
channel = 85
header.datarate = 2
header.address_length = 5
header.payload_length = 8
header.sequence_number = 0
header.no_ack = 0
header.crc_length = 2
Address = 0x55 0x55 0x55 0x55 0x55
payload = 0x20 0x20 0x20 0x20 0x32 0x30 0x2E 0x30
```

→ We would like to send this packet every 0.5s (same as the STM32 + NRF24L01+ breakout board)

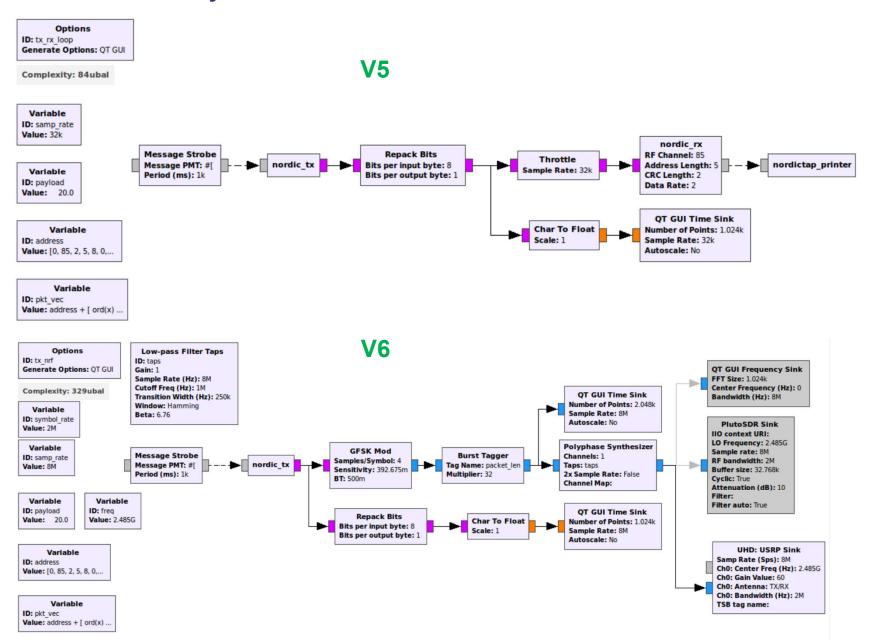
#### □ Let's build a transmitter

- → To validate the transceiver chain, build a TX/RX loop model with GRC.
- → Some tips:
  - Use a Message Strobe block as input to the nordic\_tx block



- Take care of the PMT (look at line 79 of nordic\_tx\_impl.cc)!
- → Your model is complete but it does not work...
  - Find the bug in nordic\_tx\_impl.cc!
- → OK it's working now: let's build a transmitter model.
- → Check your model with your neighbour as a receiver

#### ☐ Here are my models:

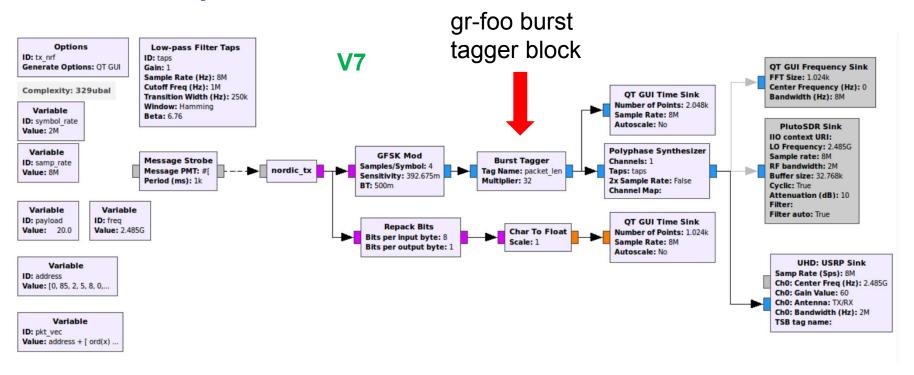


- Adding a length tag to the nordic\_tx block
- → This can be useful to synchronise vizualisation blocks
- → Edit nordic\_tx\_impl.cc and add a tag named packet\_len whose value is the length of the produced packet
- → Tips:
  - → Have a look here:

https://wiki.gnuradio.org/index.php/Guided Tutorial Programming Topics#5.2.1 A dding tags to the QPSK demodulator

- → Our packet\_len should increase because of the byte to bit conversion and the upsampling rate. How can we do that?
- → Get, build and install gr-foo (maint-3.7 branch). You will find a nice block called burst tagger!

#### ☐ Here is my model:

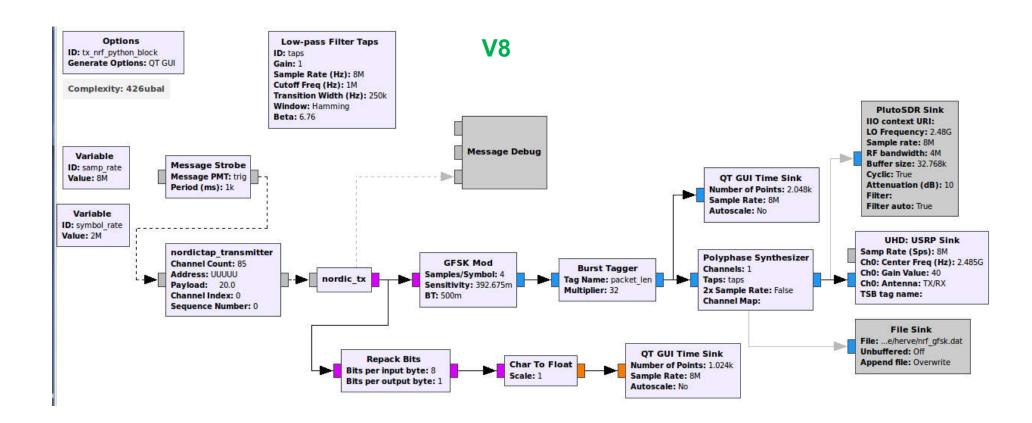


- Creating our own nordictap\_transmitter block
- → part of this block in nordic channelized\_transmitter.py

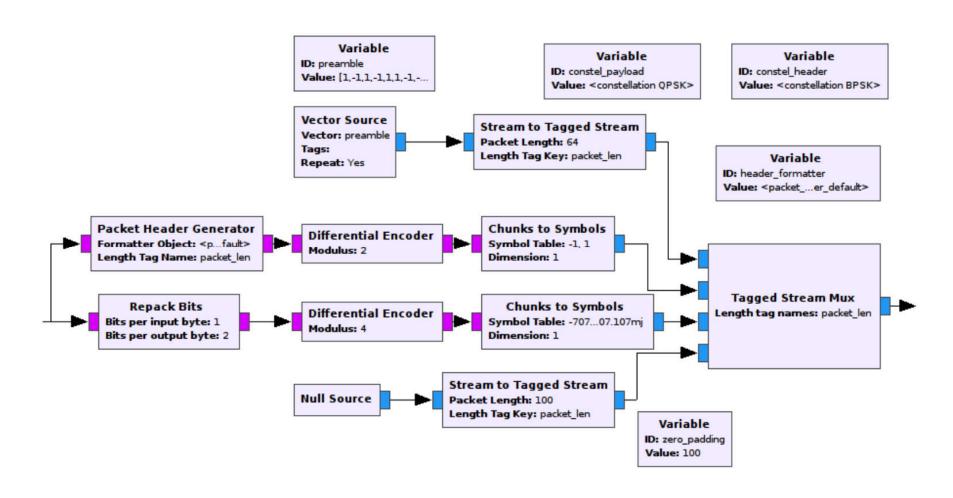


- **→** Does not meet our needs for GRC
- → We want our block to be triggered by a message strobe block
- → User can enter easily packet data from GRC block
- → Write this block and add it to nordic\_blocks.py
- → Create the associated GRC nordic\_nordictap\_transmitter.xml
- →Add your block to the GRC transmitter model and check that everything works

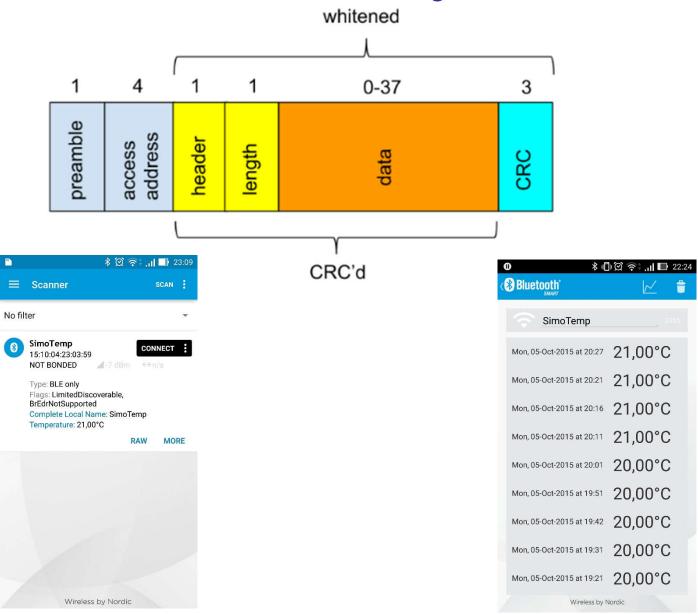
#### ☐ Here is my model:



#### ☐ Can we build the TX with existing GNU Radio blocks?



#### ☐ Homework: build a BLE Advertiser with gr-nordic blocks



## Outline

1 -

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4 - Conclusion

#### 4. Conclusion

- □Logitech research firmware demo
- □ How to increase your knowledge in GNU Radio: the electronics engineer's point of view
- **□GNU Radio Packet Communications**
- **□**Several OOT implementations available:
  - gr-burst (Tim O'Shea)
  - gr-eventstream (Tim O'Shea) → example fsk mod/demod or psk mod/demod
  - Digital communication point of view
  - gr-packetizer (Thomas Verelst)

# THANK YOU FOR YOUR ATTENTION!

### References

[1] https://wiki.gnuradio.org/index.php/Tutorials